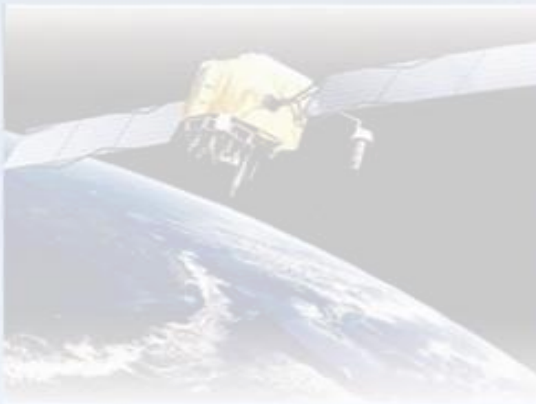




Surveying 1 / Dr. Najeh Tamim

CHAPTER 4

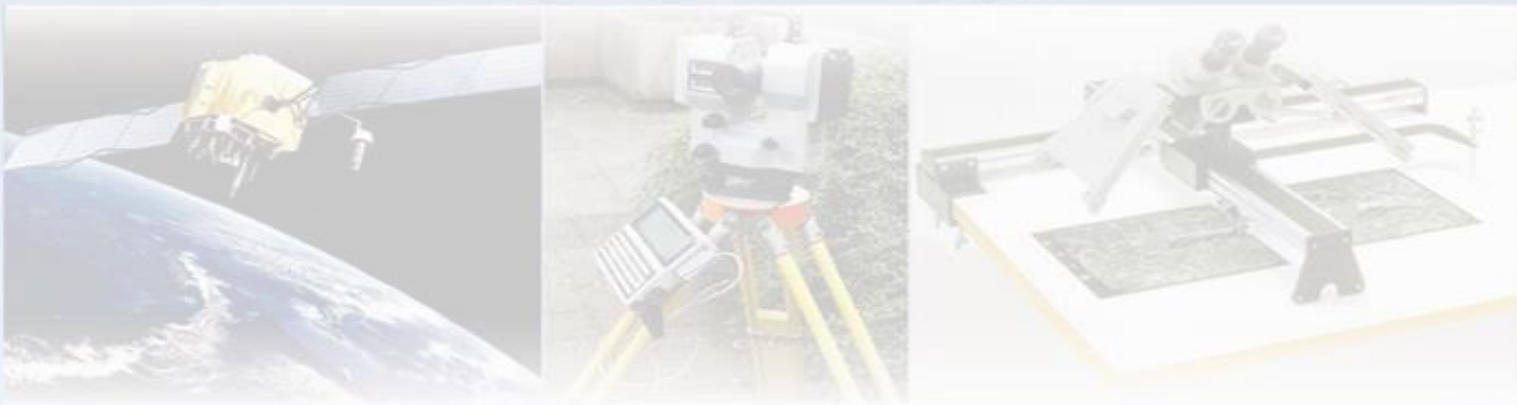
LEVELING





4.1 INTRODUCTION

- Elevation (Height) of a point is defined as the vertical distance between the point and a reference level surface called *datum*.
- Why do we need to know elevations?





Methods of Leveling:

- Chain Surveying
- Barometric Leveling
- Trigonometric Leveling
- Photogrammetric Leveling
- GPS Leveling
- Differential Leveling





4.2 BASIC DEFINITIONS

- *Vertical line.*
- *Horizontal line.*
- *Horizontal plane.*
- *Level surface.*
- *Level line.*
- *Difference in elevation between two points.*
- *Actual line of sight or collimation*
- *Bench mark (BM).*

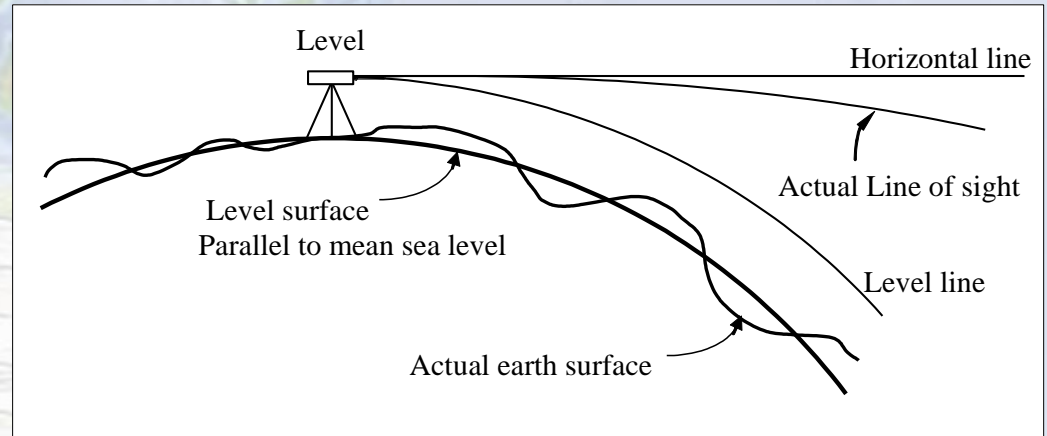


FIGURE 4.1: Relationship between the horizontal line, level line and the line of sight

MSL
Geoid

Level
Surfaces

B

A

ΔH

A

B

ΔH

MSL

MSL
Geoid

Level
Surfaces

B

A

ΔH

A

B

ΔH

MSL

MSL
Geoid

Level
Surfaces

B

A

ΔH

A

B

ΔH

MSL



4.3 BASIC PRINCIPLE OF A LEVEL

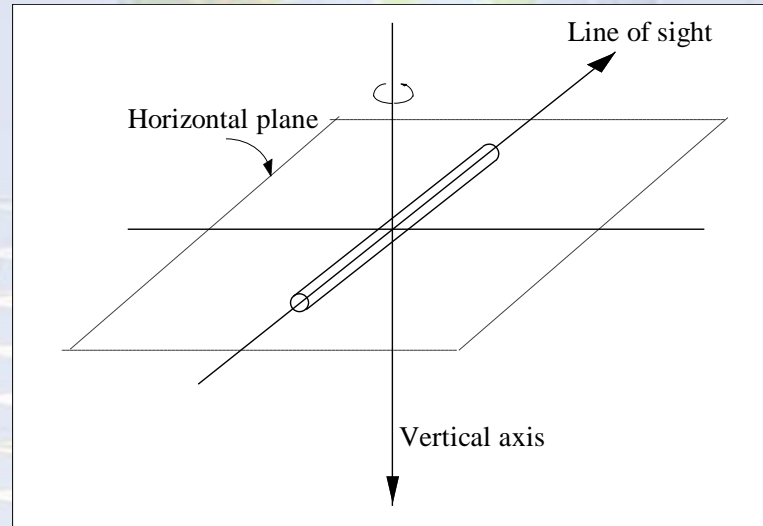


FIGURE 4.2: Basic principle of a level.

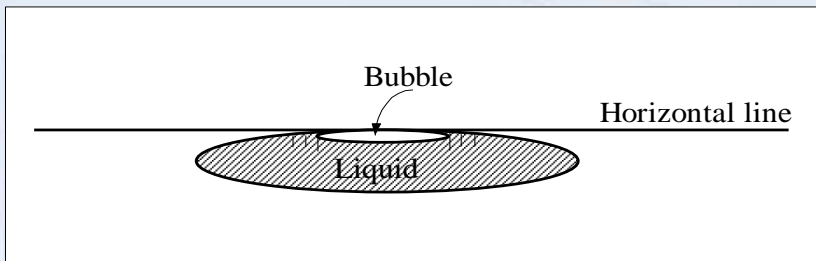


FIGURE 4.3: Cross section in a bubble tube.

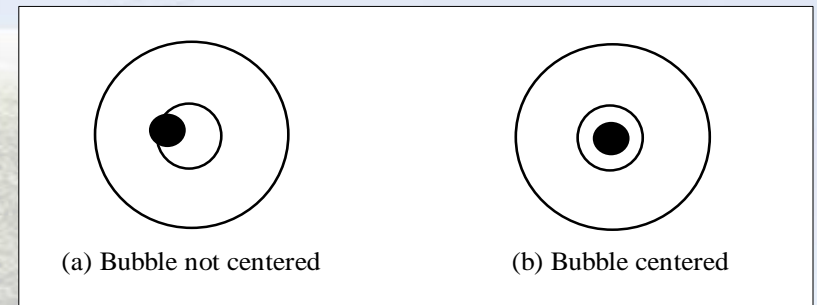
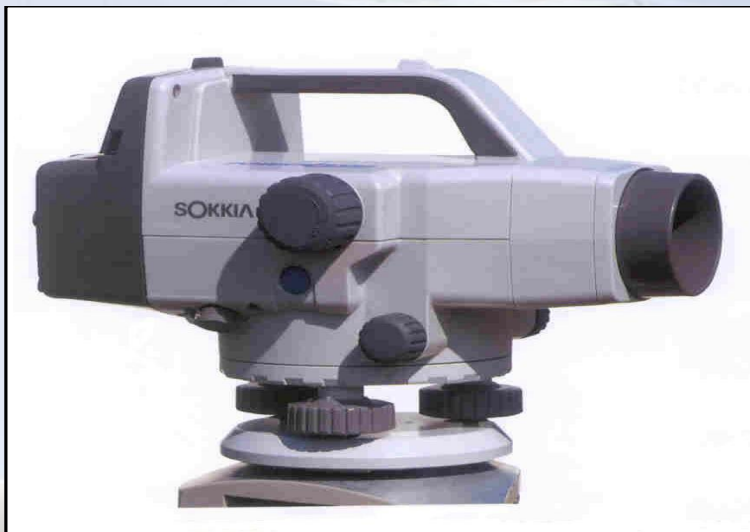


FIGURE 4.4: Centering the bubble.



4.5 EQUIPMENT USED IN DIFFERENTIAL LEVELING

- The Level.



(a) Automatic level.



(b) Electronic digital level.

FIGURE 4.6: Automatic and electronic digital Levels.

- Tripod



(a) Fixed leg tripod

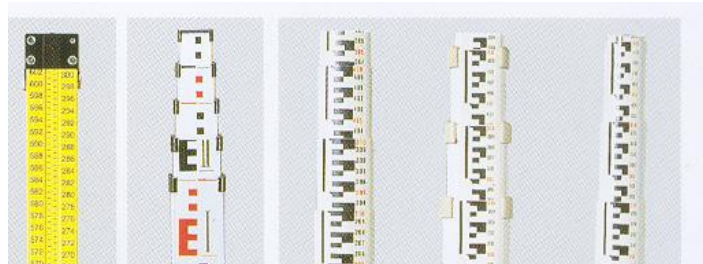


Hard Wood

Aluminum

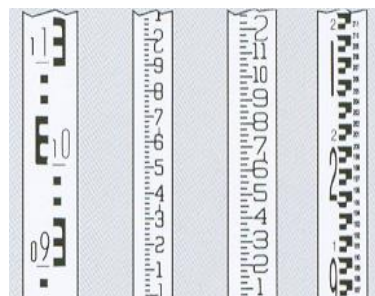
(b) Extension leg tripod

- Leveling Staves



(c) Leveling staves

- Leveling Rod



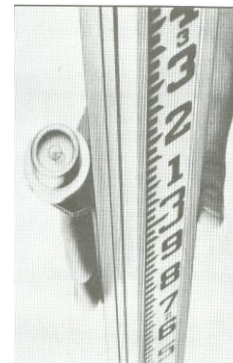
Metric

Feet

Feet

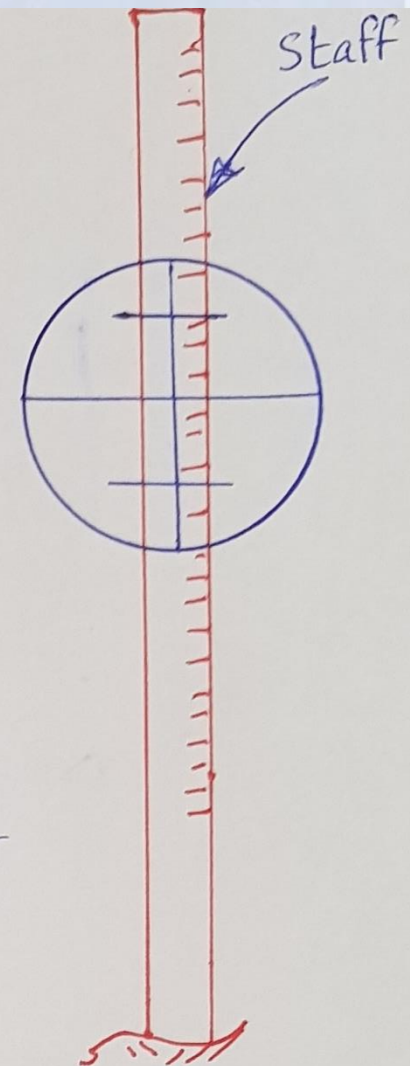
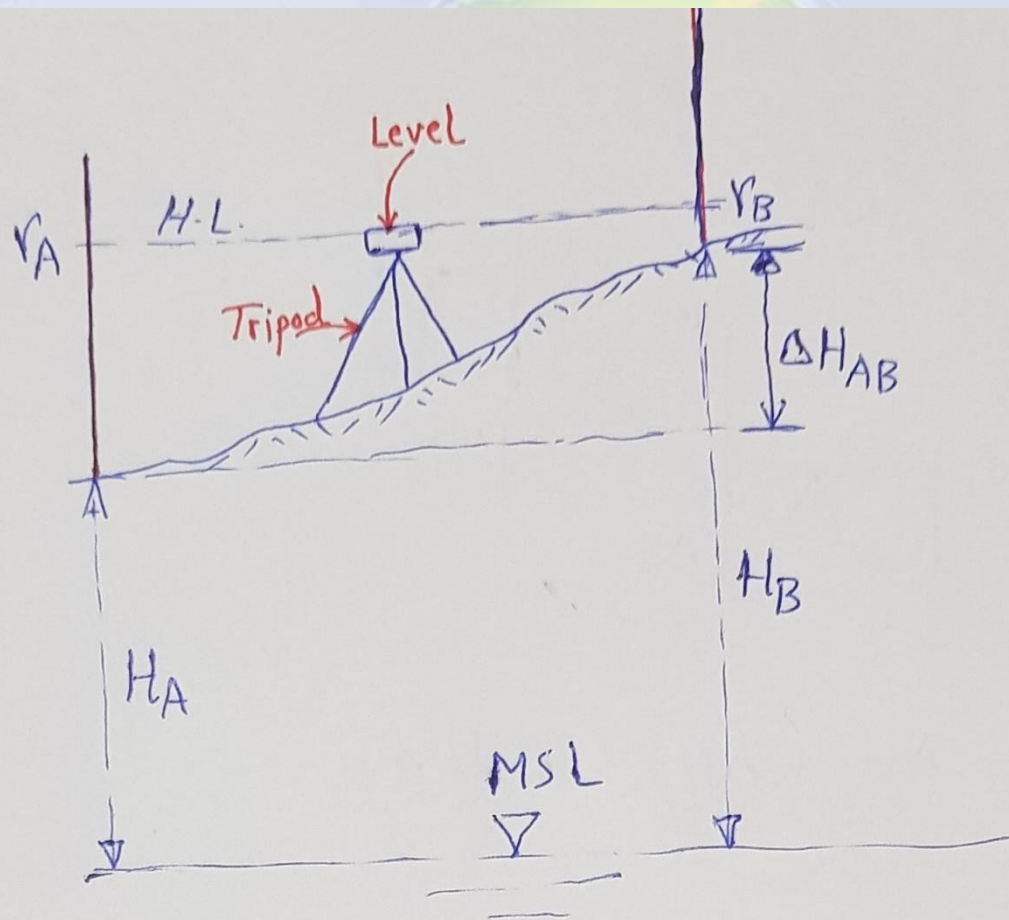
Metric

(d) Metric and feet graduations of

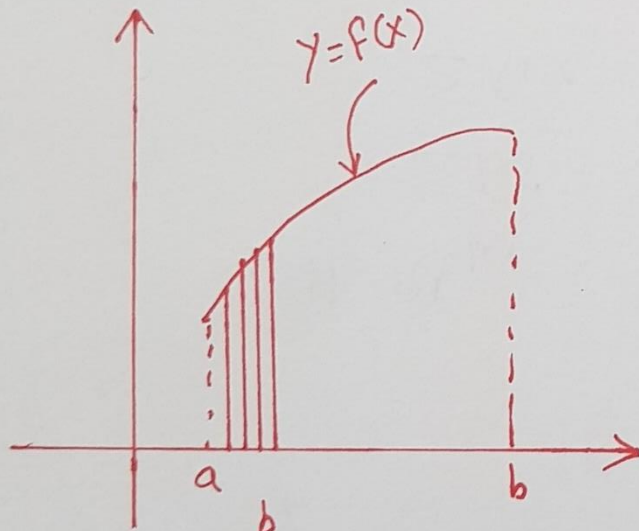


(e) Rod level

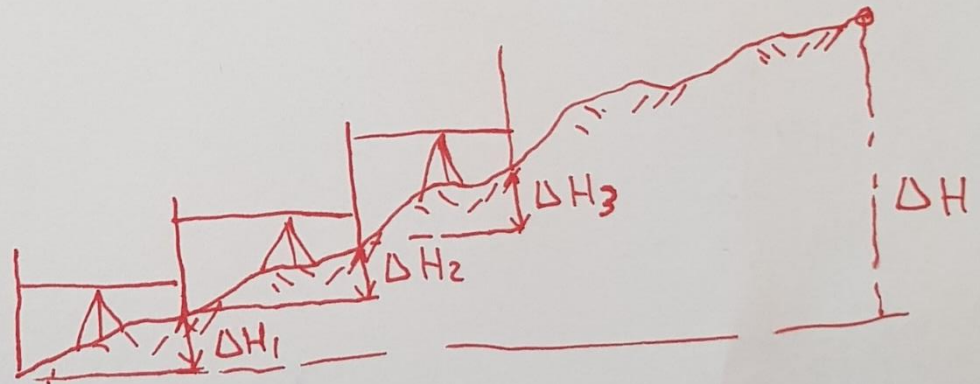
FIGURE 4.7: Tripods, leveling staves and rod levels.



$$\begin{aligned}\Delta H_{AB} &= H_B - H_A \\ &= V_A - V_B\end{aligned}\quad (p.89)$$



$$A = \int_a^b f(x) \cdot dx$$



$$\Delta H = \Delta H_1 + \Delta H_2 + \Delta H_3 + \dots$$

(Differential Leveling)



4.6 SETTING UP THE LEVEL

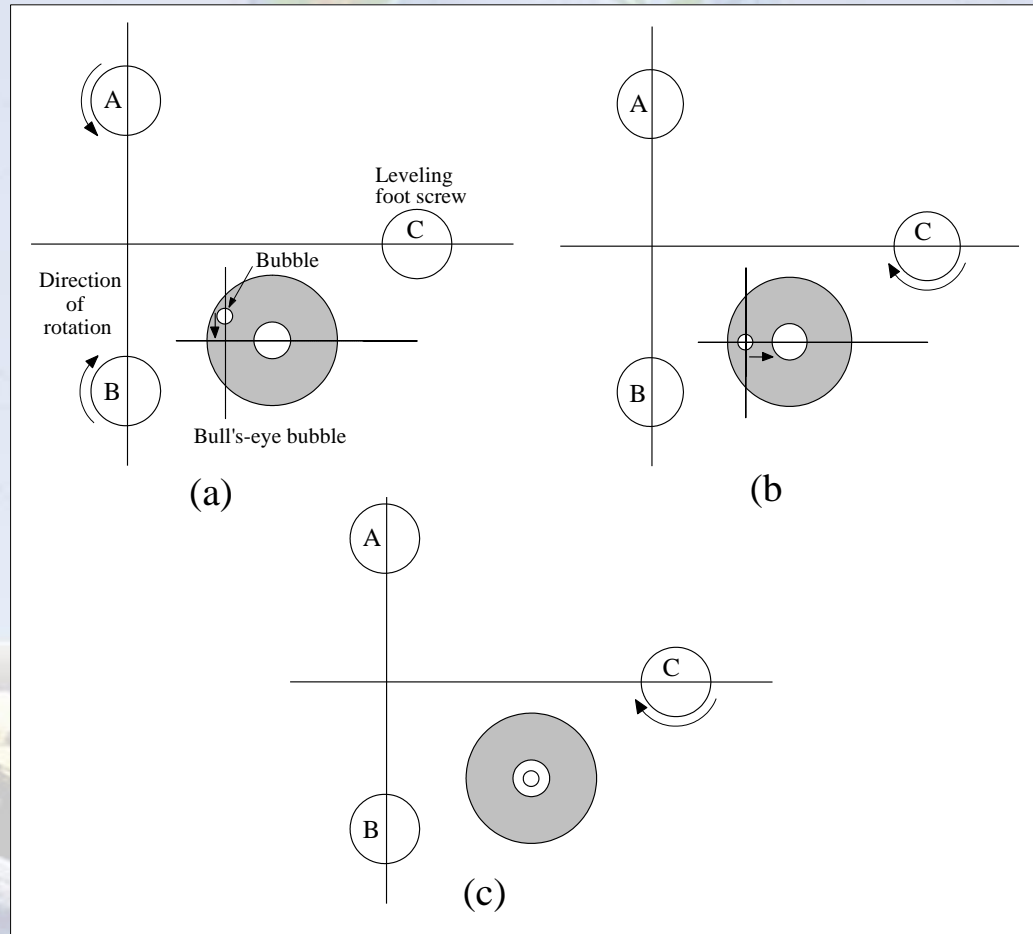


FIGURE 4.8: Leveling an instrument with three foot screws and a circular bubble tube.

4.7 MEASURING ELEVATION DIFFERENCE USING A LEVEL

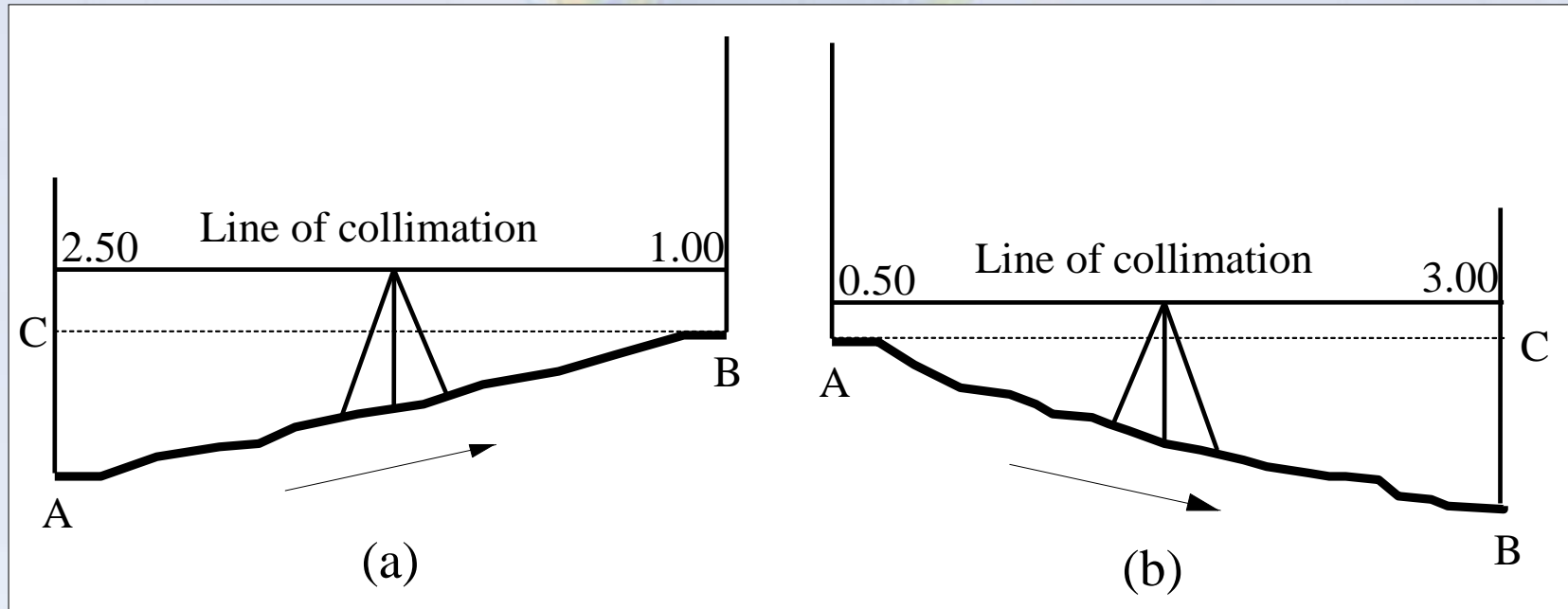
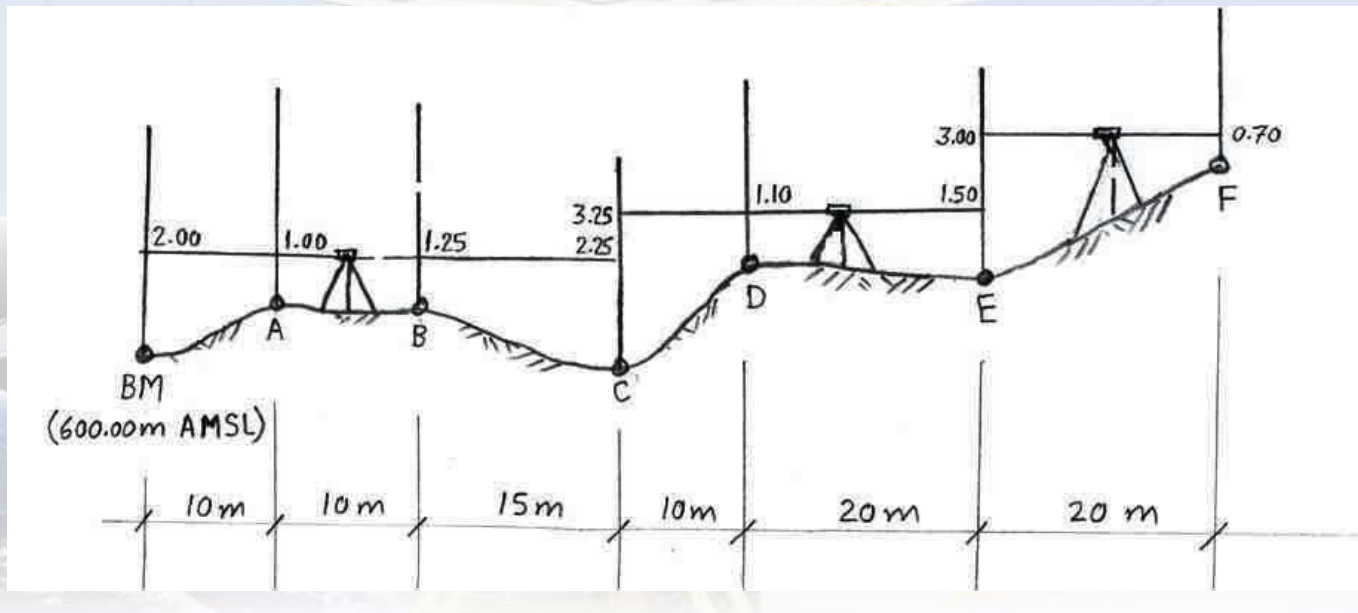


FIGURE 4.9: Principle of differential leveling.



4.8 PROCEDURE IN DIFFERENTIAL LEVELING

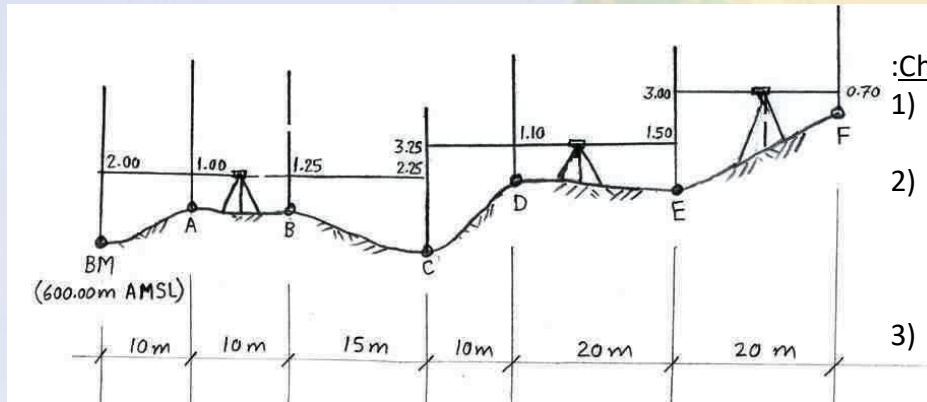
- *Backsight (BS).*
- *Foresight (FS).*
- *Intermediate Sight (IS).*
- *Turning Point (TP).*







General Procedure: Example



:Checks

1) # of BS = # of FS = # of setups \Rightarrow OK

2) Σ BS - Σ FS = 8.25 - 4.45 = 3.80

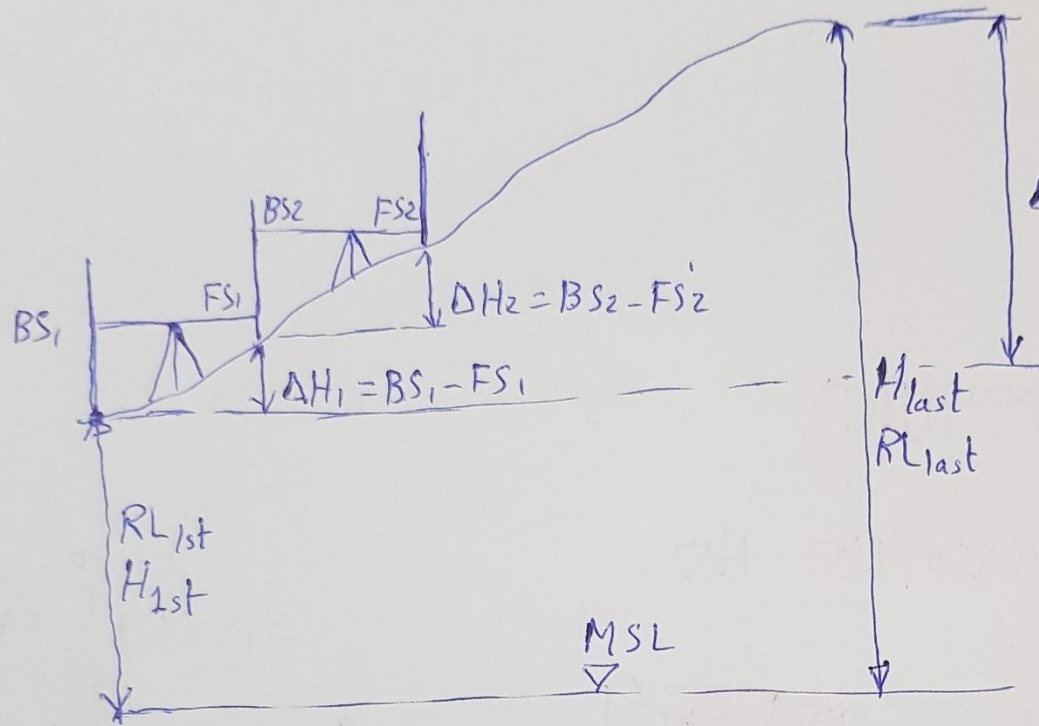
Σ Rise - Σ Fall = 5.45 - 1.65 = 3.80 \Rightarrow OK

$RL_{last\ pt} - RL_{1st\ pt} = 603.80 - 600.00 = 3.80$

3) $601.00 + 600.75 + 599.75 + 601.90 + 601.50 + 603.80 = 3608.70$

$602.00 \times 3 + 603.00 \times 2 + 604.50 \times 1 - 3.35 - 4.45 = 3608.70 \Rightarrow$ OK

Point #	BS	IS	FS	Rise	Fall	HI	RL	Distance	Remarks
BM	2.00					602.00	600.00	0	BM
A		1.00		1.00			601.00	10	
B		1.25			0.25		600.75	20	
C	3.25		2.25		1.00	603.00	599.75	35	TP
D		1.10		2.15			601.90	45	
E	3.00		1.50		0.40	604.50	601.50	65	TP
F			0.70	2.30			603.80	85	
Σ	8.25	3.35	4.45	5.45	1.65				



$$\Delta H = \Delta H_1 + \Delta H_2 + \dots$$

$$= \sum BS - \sum FS$$

$$\Delta H = RL_{last} - RL_{1st}$$

$$= \sum BS - \sum FS$$

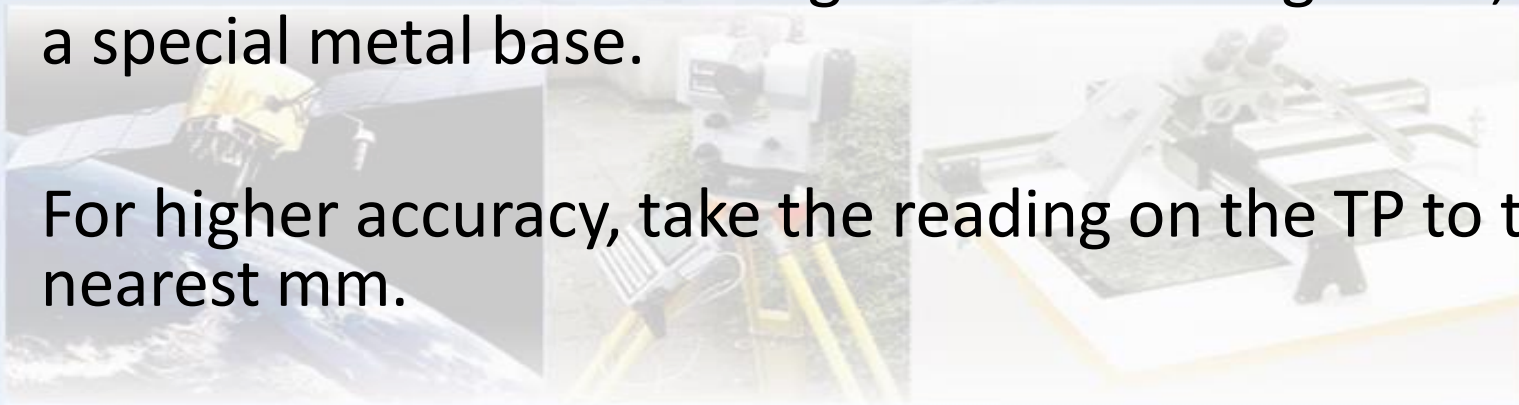
$$= \sum Rise - \sum Fall$$



4.9 GENERAL NOTES

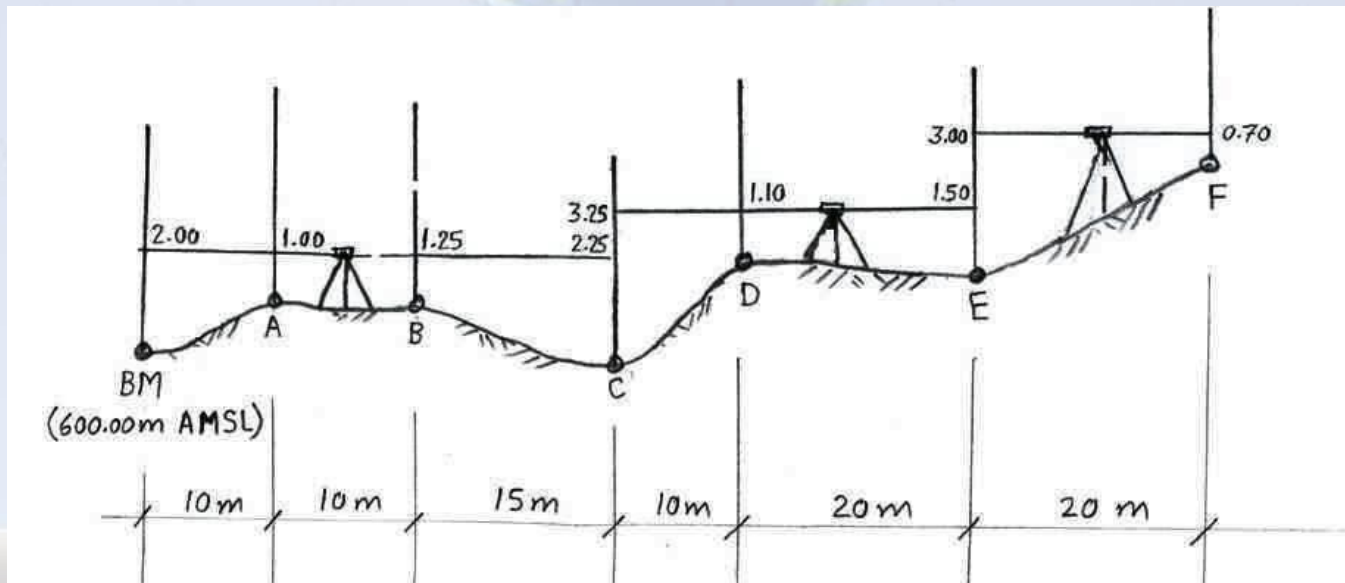


- Start leveling from a BM and end it at another BM, or go back and close at the starting point.
- If only ΔH is needed between the first and last points, no need to take IS.
- Equal BS and FS distances.
- Choose TP to be on a firm ground. On soft ground, use a special metal base.
- For higher accuracy, take the reading on the TP to the nearest mm.



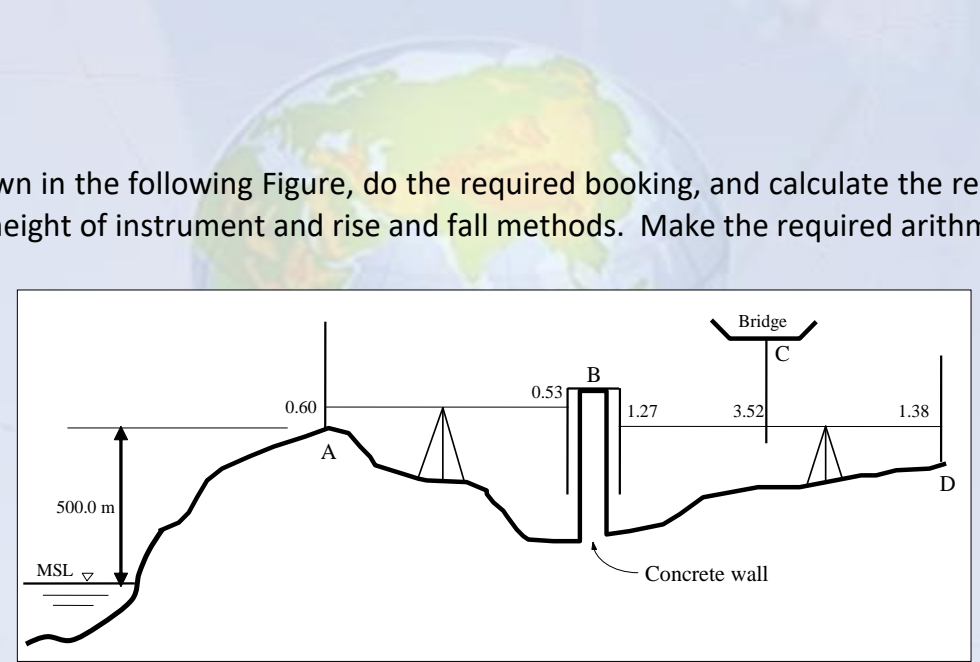


- Leveling does not have to start from a BM. The BM could be the last point, or a point on the way of the leveling chain.



- If the point is above the line of sight, the reading is taken with the staff upside-down and registered as a –ve value.

Following Figure, do the required booking, and calculate the rise and fall methods. Make the re



Point	BS	IS	FS	Rise	Fall	HI	RL	Notes
A	0.60					500.60	500.00	BM
B	-1.27		-0.53	1.13		499.86	501.13	Top of concrete wall (TP)
C		-3.52		2.25			503.38	Bottom of bridge
D			1.38		4.90		498.48	
SUM	-0.67	-3.52	0.85	3.38	4.90			

Checks:

- 1) # of BS = # of FS = 2 \Rightarrow OK
- 2) $\Sigma BS - \Sigma FS = -0.67 - 0.85 = -1.52$
 $\Sigma Rise - \Sigma Fall = 3.38 - 4.90 = -1.52 \Rightarrow$ OK
 $RL_{last} - RL_{1st} = 498.48 - 500.00 = -1.52$



4.10 ERRORS IN DIFFERENTIAL LEVELING

- a) Systematic errors:

1. Inclination of the line of sight due to the earth's curvature and atmospheric refraction.

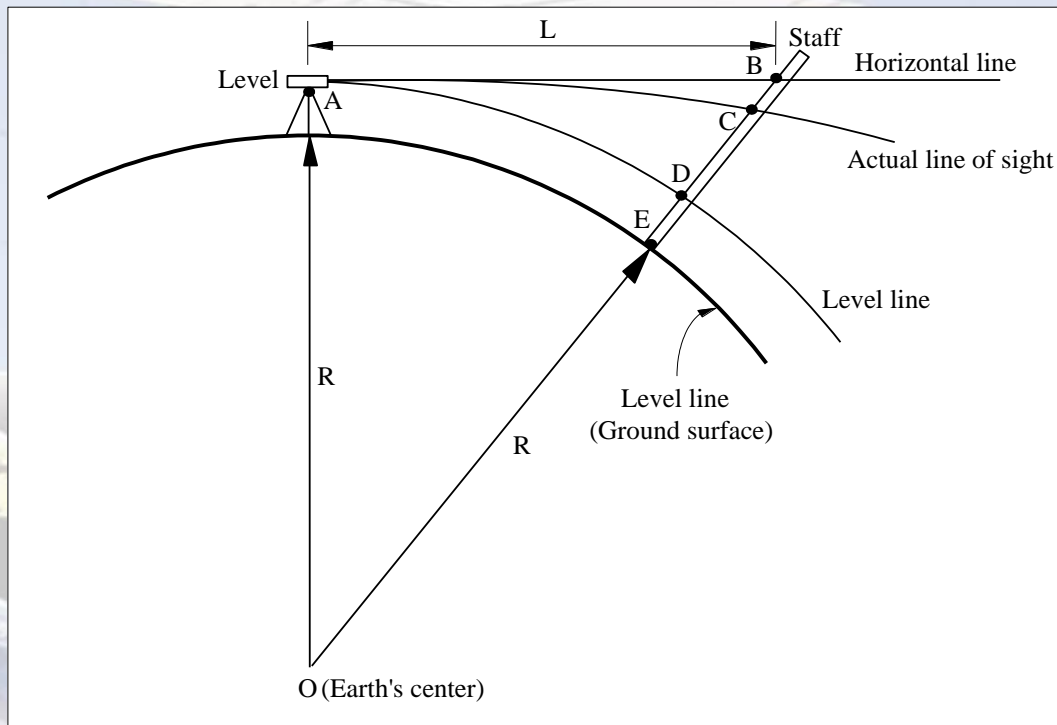


FIGURE 4.12: Effect of earth's curvature and atmospheric refraction on differential leveling.



2) Inclination of the line of sight due to maladjustment of the level.

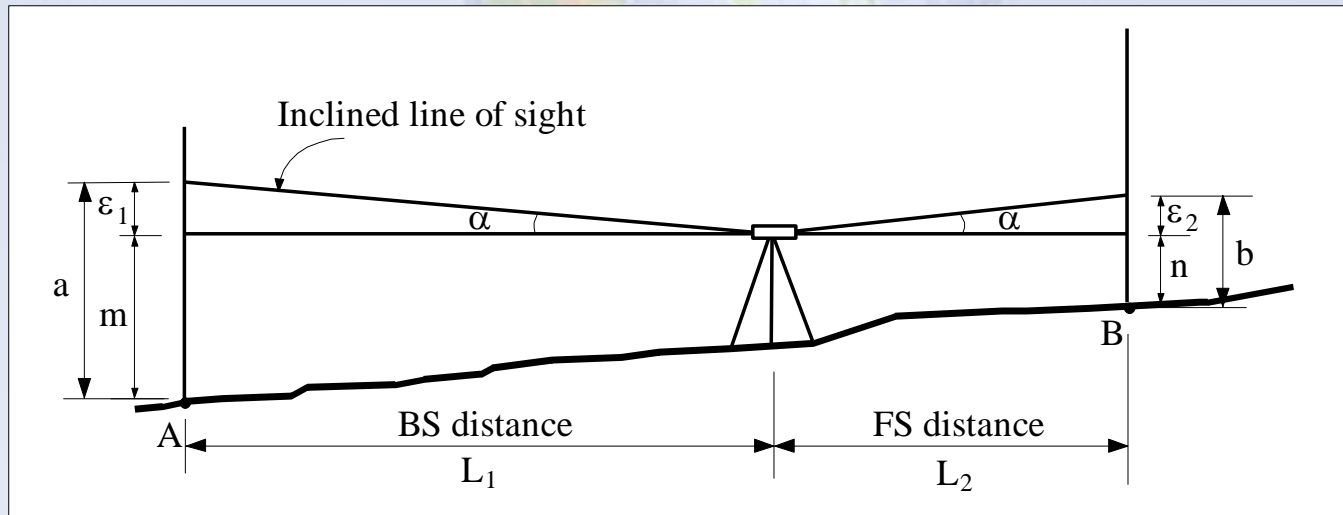


FIGURE 4.13: Error due to the maladjustment of the level.

b) Random errors

c) Blunders or mistakes



4.11 RECIPROCAL LEVELING

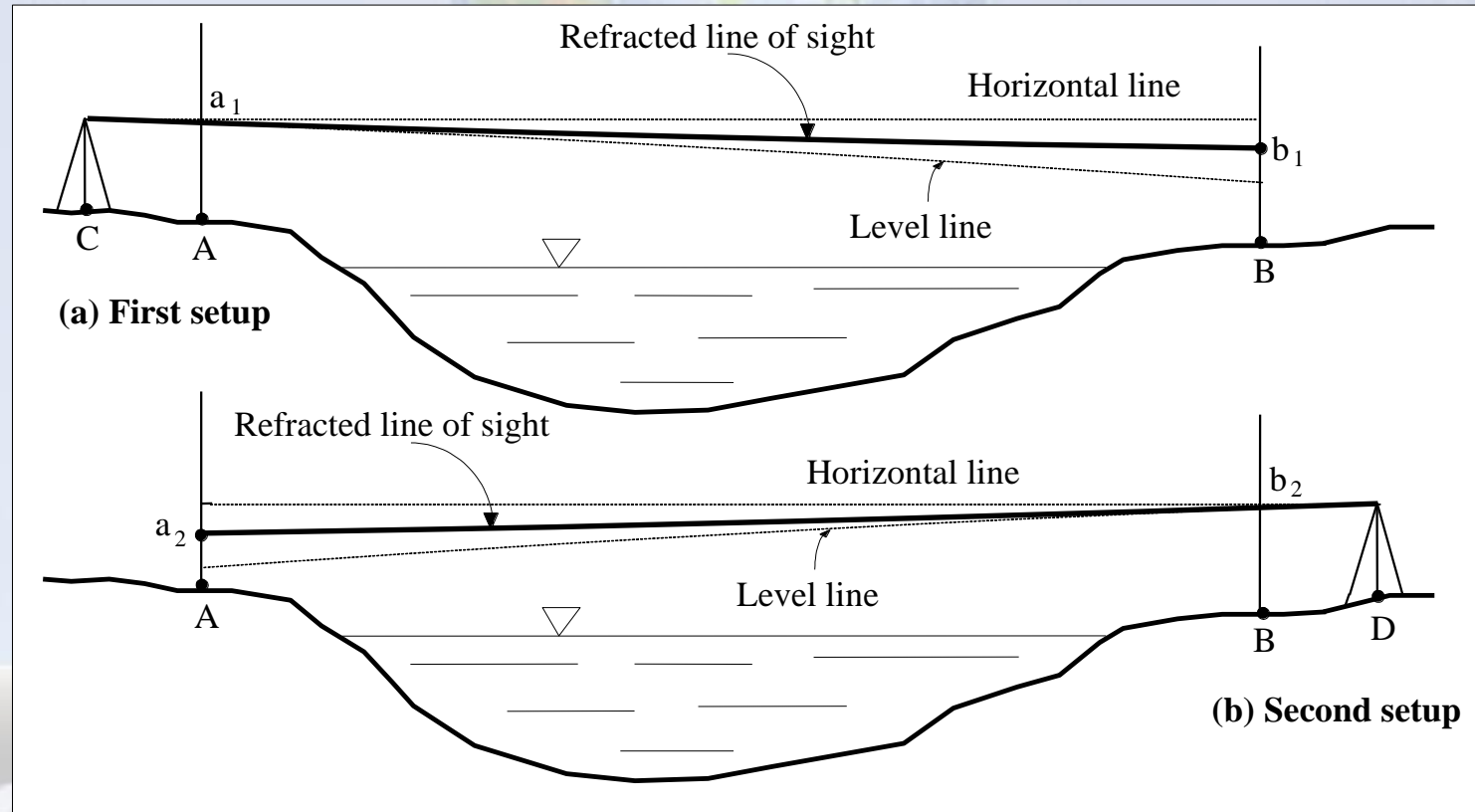


FIGURE 4.15: Reciprocal leveling.



4.12 CLOSURE ERROR

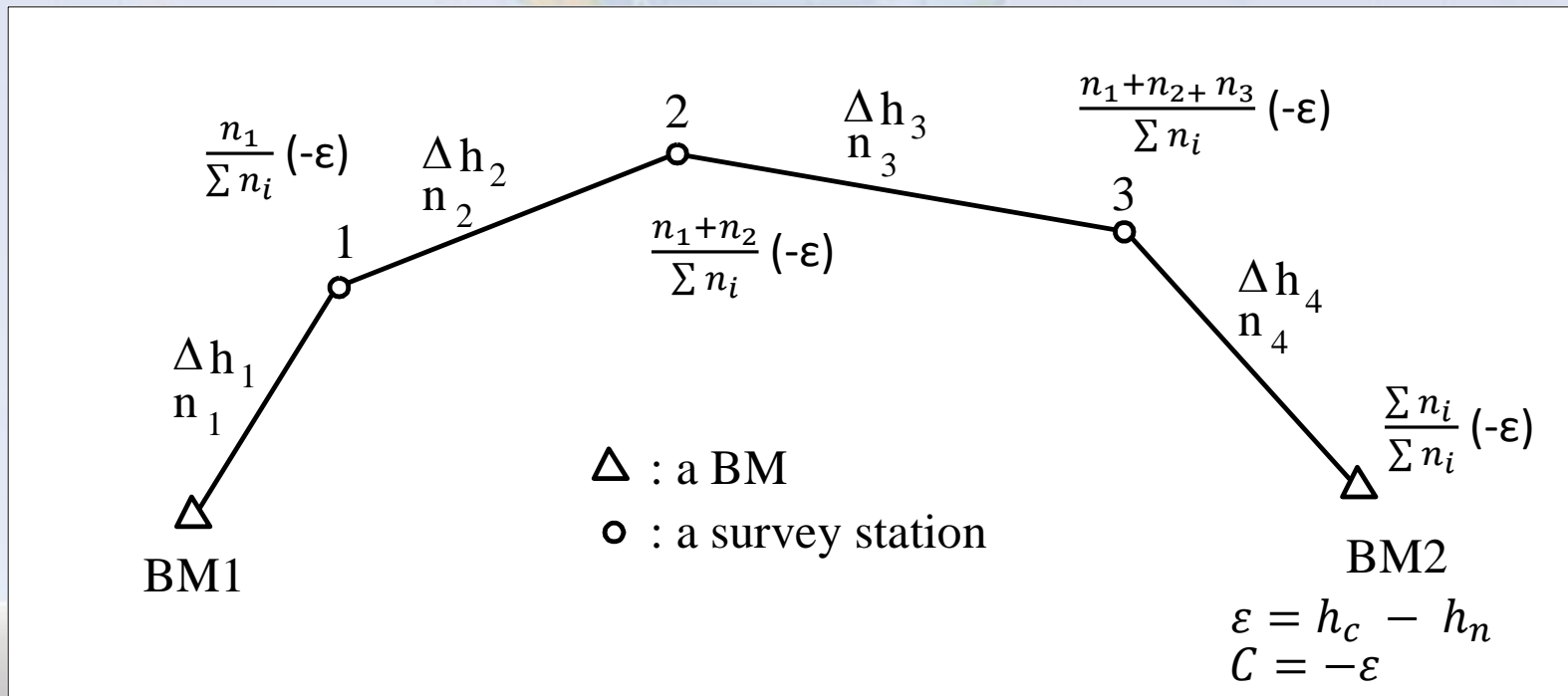


FIGURE 4.16: A level line which starts at a BM and closes at a different BM.

4.13 CLASSES AND ACCURACY OF LEVELING



- Precise Leveling.
- Ordinary Leveling.

$$\varepsilon = \pm k\sqrt{D}$$

$k = 2-5 \text{ mm (precise)}$
 $= 10-30 \text{ mm (ordinary)}$





4.14 APPLICATIONS OF LEVELING

1) LONGITUDINAL SECTIONS (PROFILES):

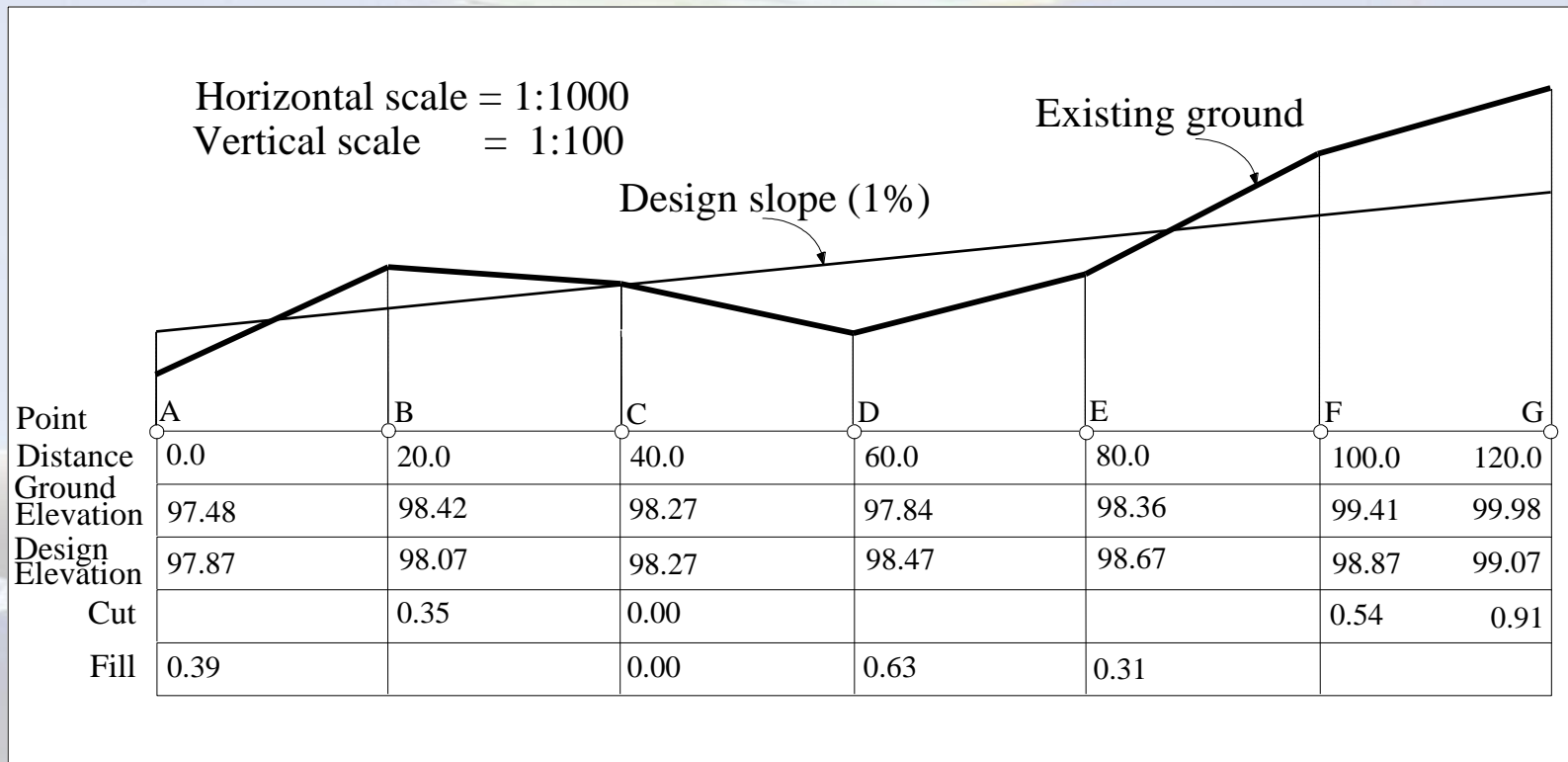


FIGURE 4.17: A longitudinal section (profile) of the data of Table 4.2.

2) CROSS-SECTIONS:

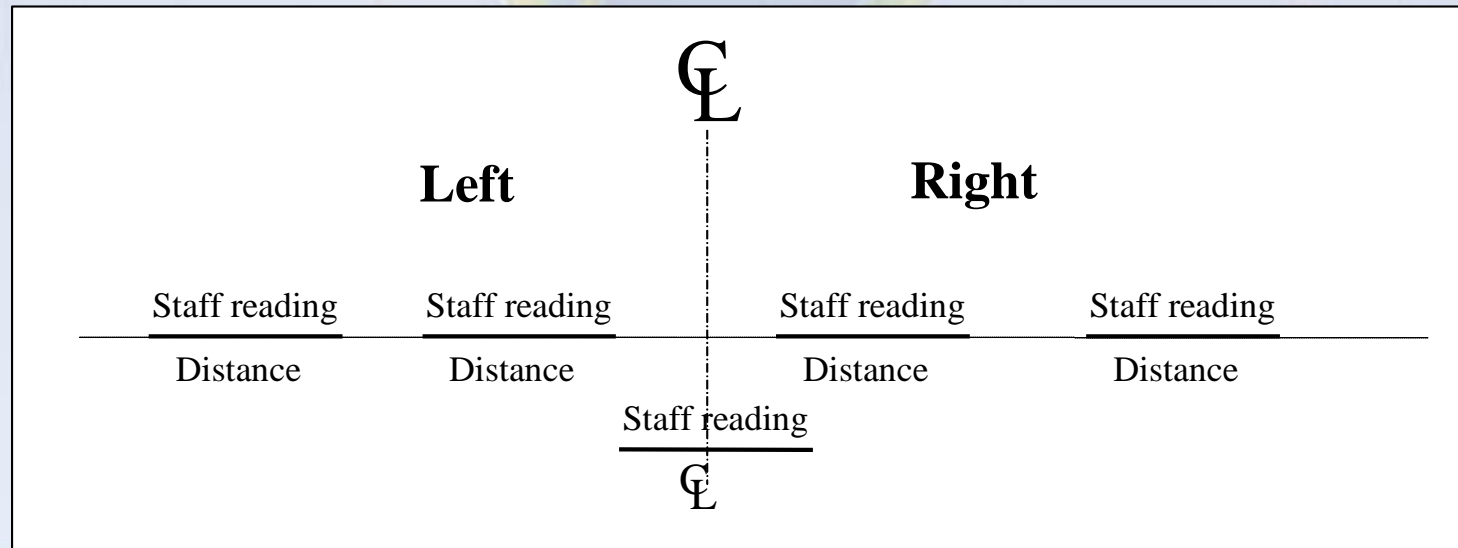


FIGURE 4.18: Booking leveling data for making cross-sections.



3) CONTOURING:

A *contour* is an imaginary line connecting points on the ground that have the same elevation.

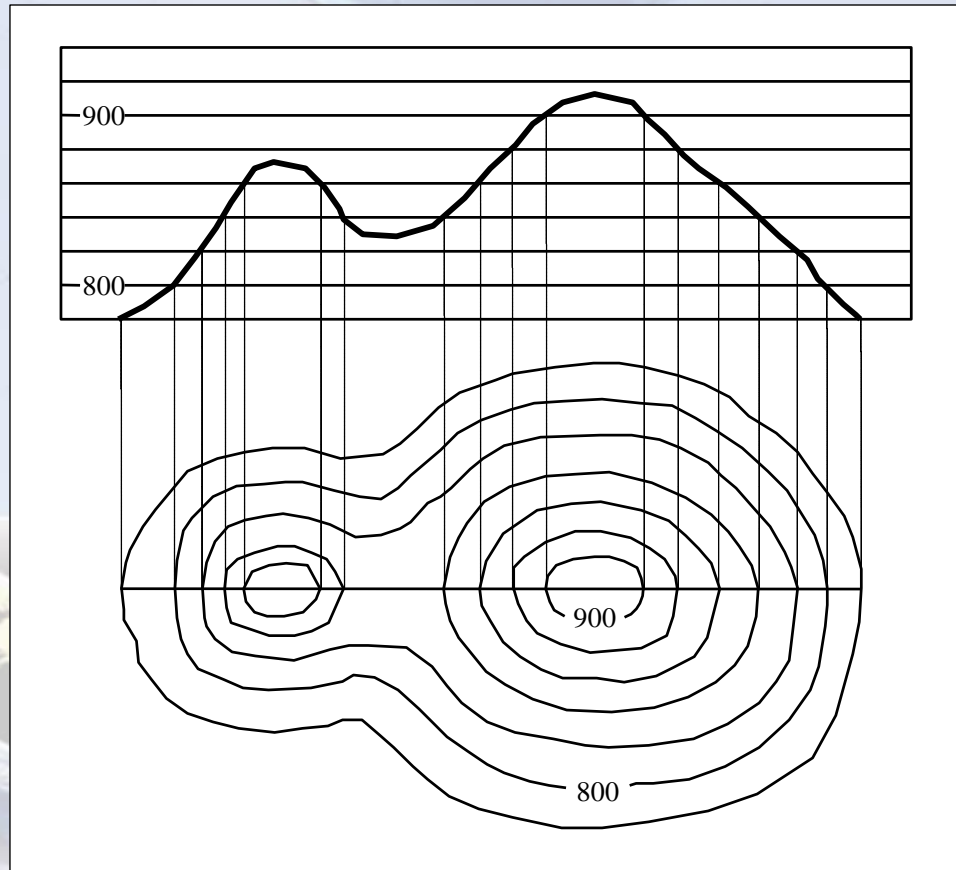


FIGURE 4.19: Contours and ground profile.

Characteristics of Contours:

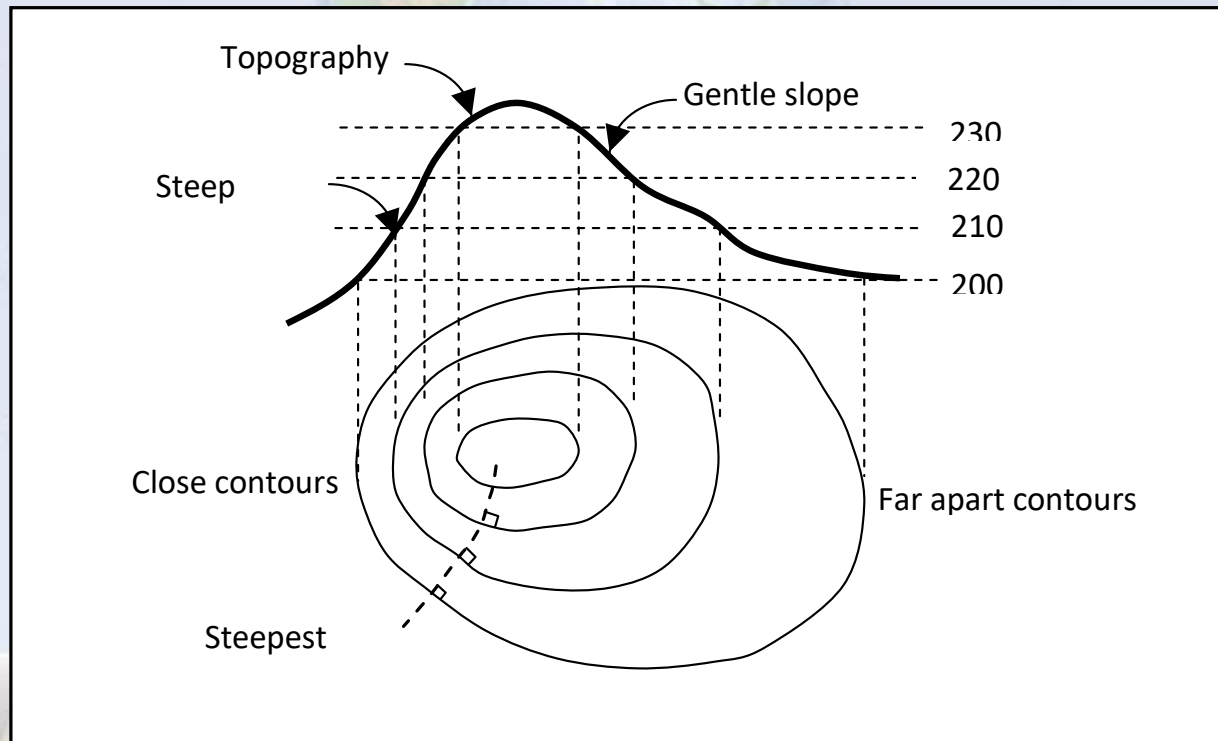


FIGURE 4.20: Relationship between contour spacing and topography slope.

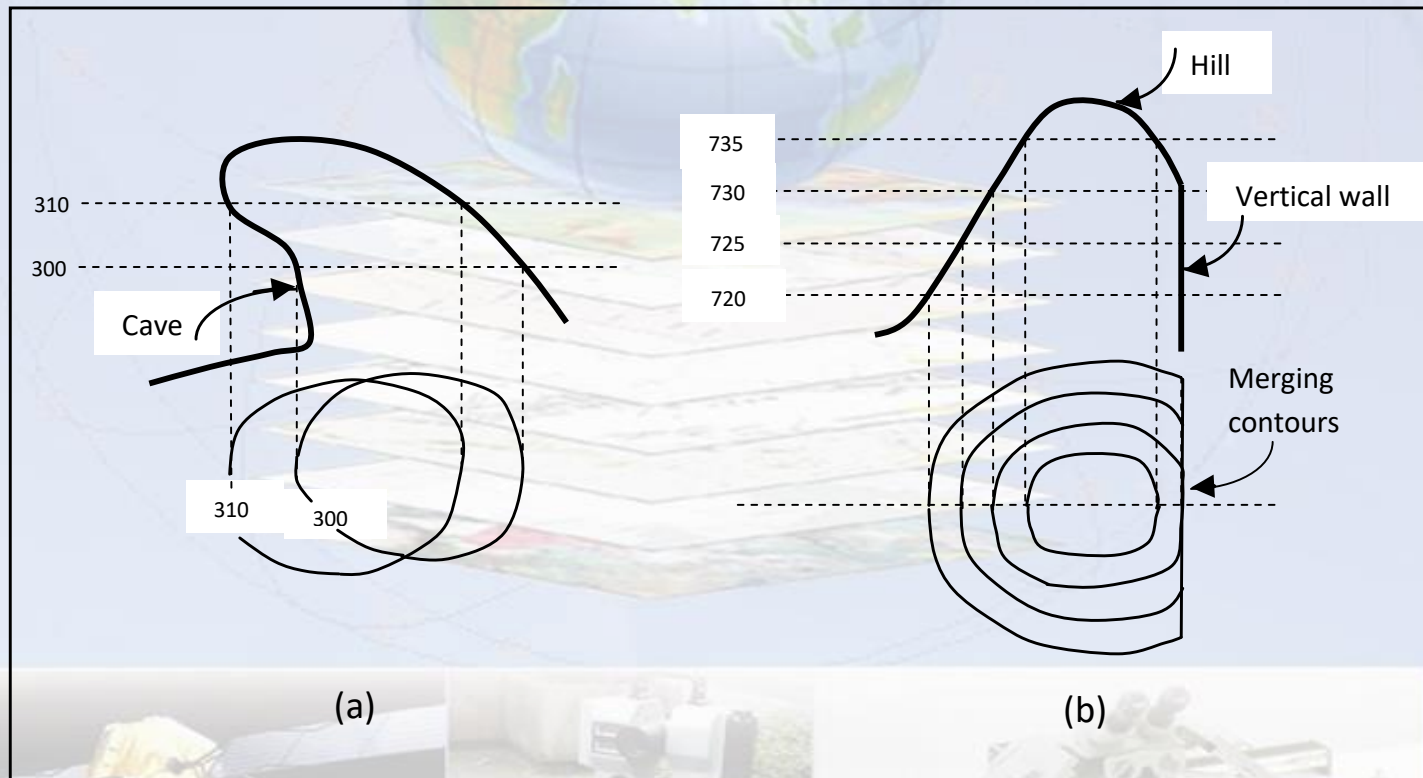
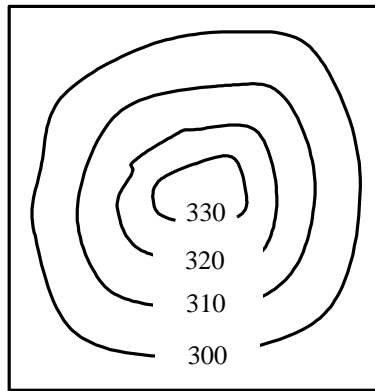
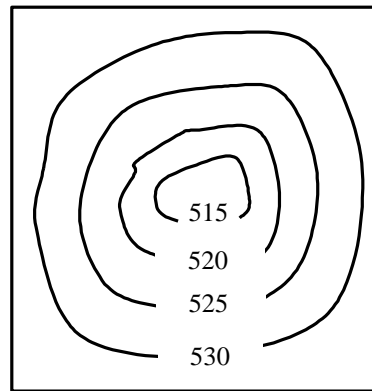


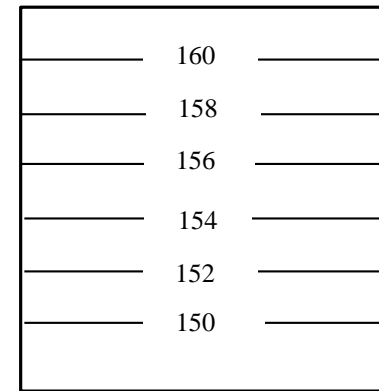
FIGURE 4.21: Examples of intersecting and merging contours.



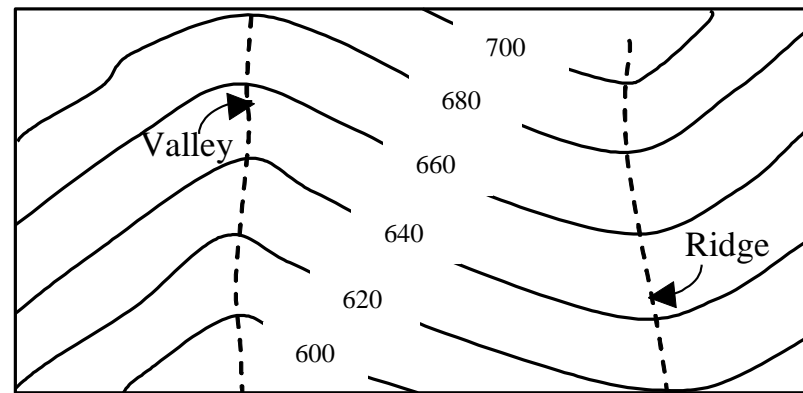
(a) Hill



(b) Depression



(c) Uniformly sloping ground

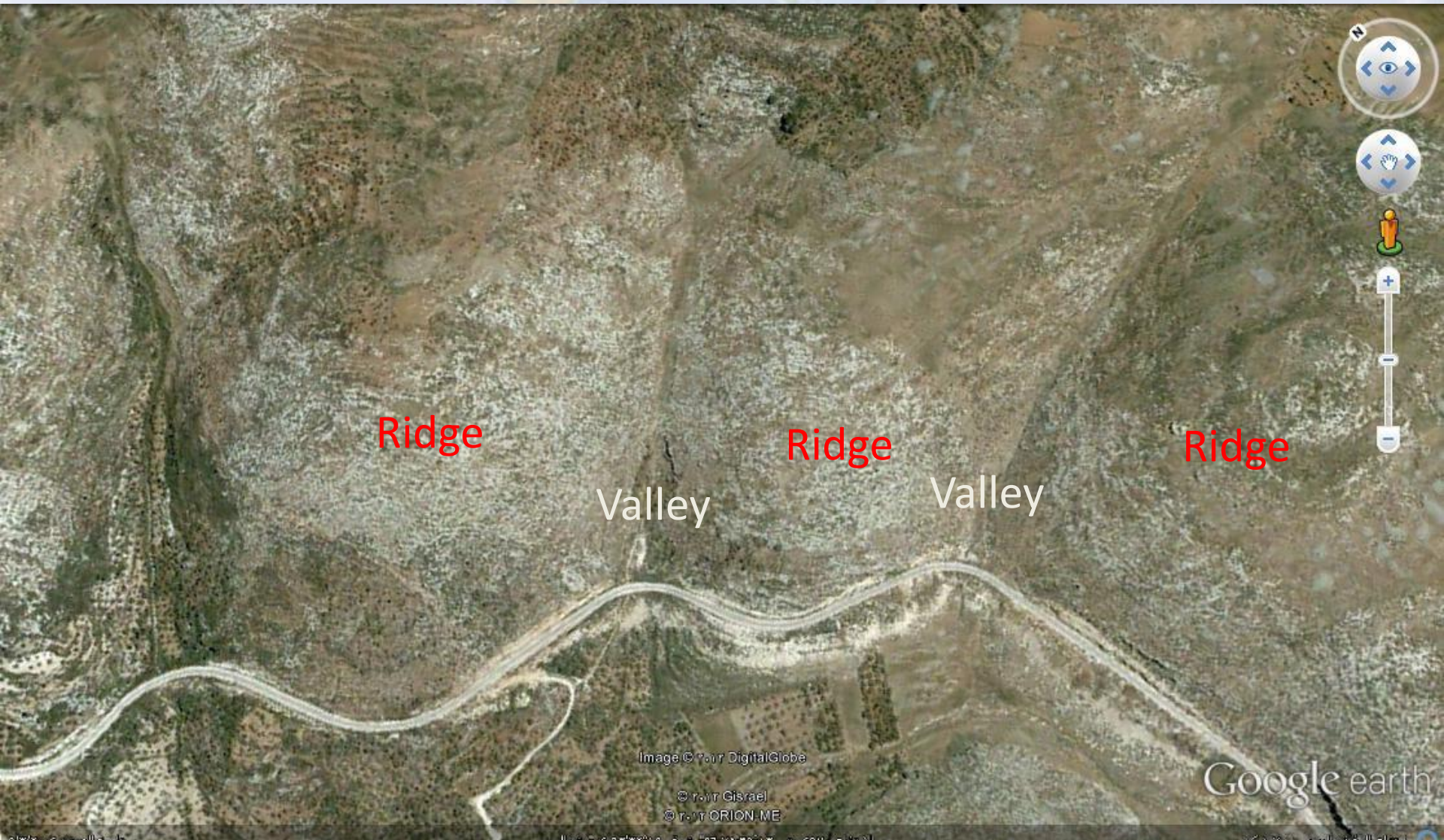


(d) Ridge and valley.

FIGURE 4.22: Examples of contours for different types of terrain.

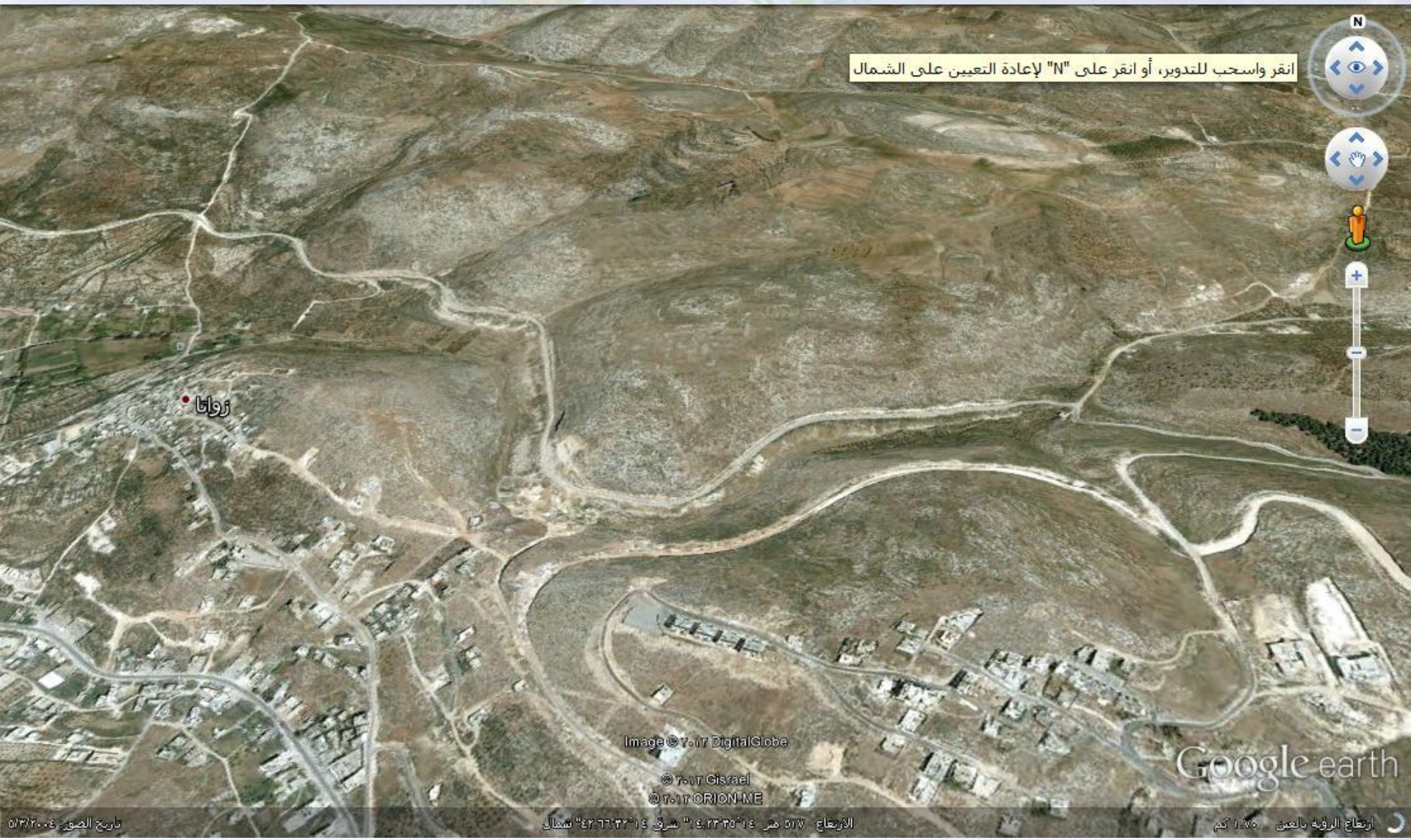
Ridge and Valley

View 1



Ridge and Valley

View 2



انقر واسحب للتدوير، أو انقر على "N" لإعادة التعيين على الشمال

زواتا

Image © 2017 DigitalGlobe

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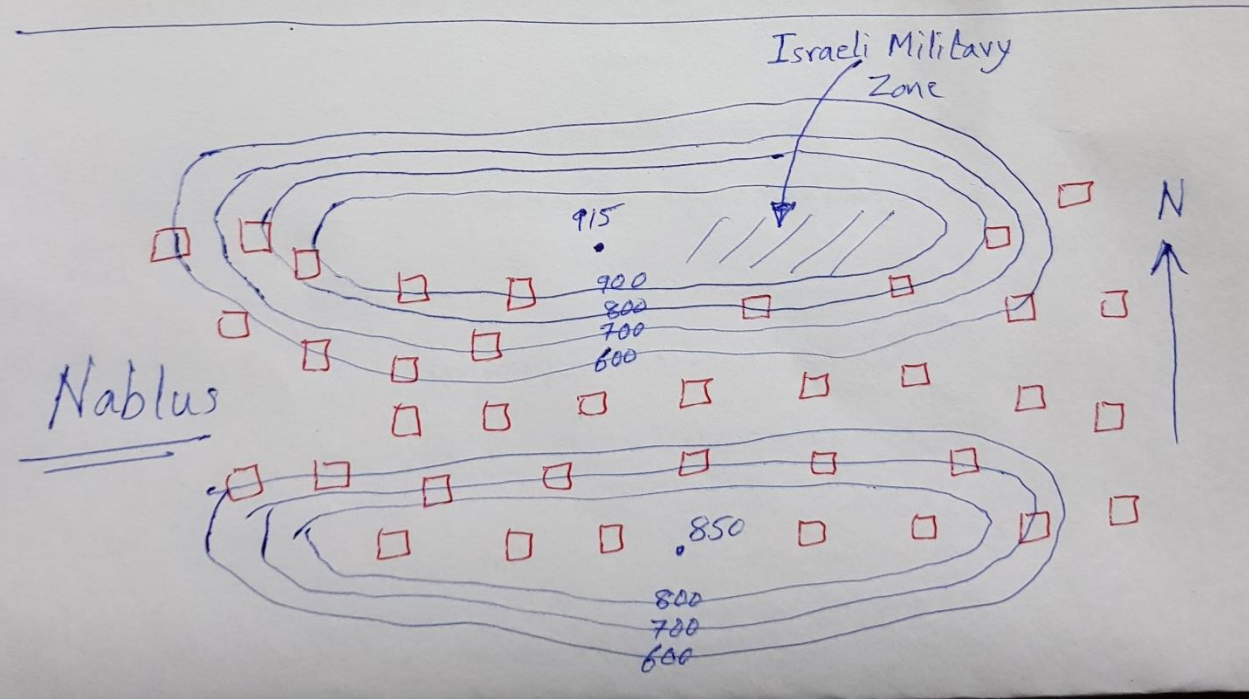
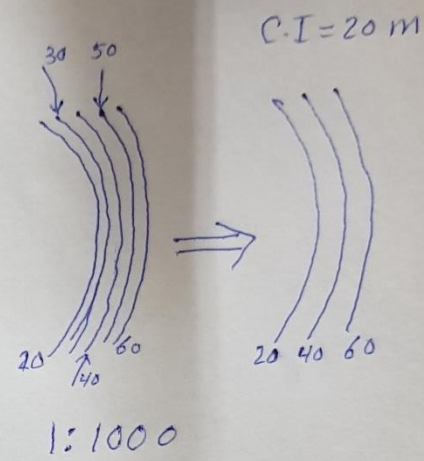
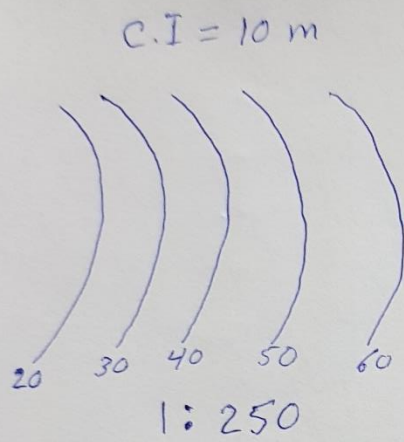
Google earth

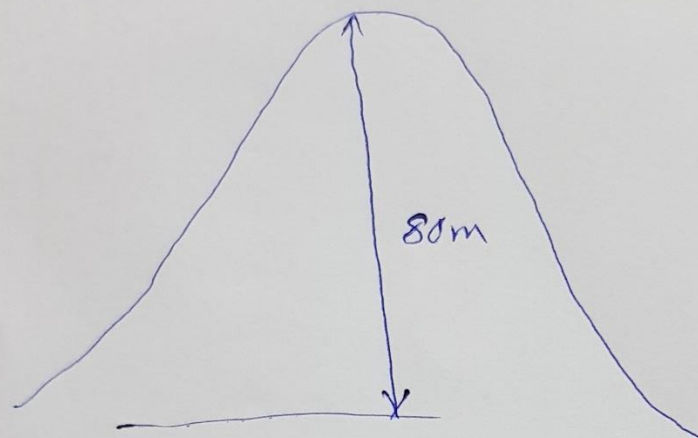


Factors affecting the choice of contour intervals:

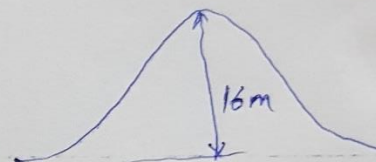
- Scale.
- Importance and purpose for which the plan is to be used.
- Accuracy, time and cost of the contour plan.
- Topographic variation of the area.
- Size of the area.



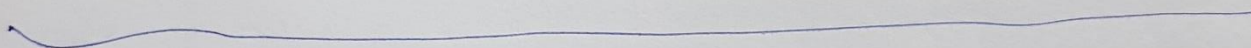




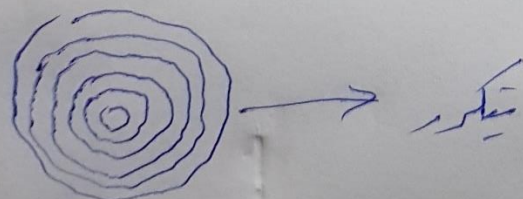
C.I. = 10 m



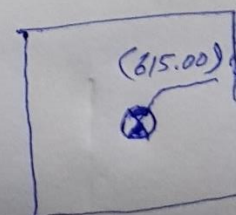
C.I. = 2 m



نقطه
مربع



C.I. = 1 m



Flat area

Gridding:

$$\frac{x}{12} = \frac{1.2}{1.6} \Rightarrow x = 8 \text{ m}$$

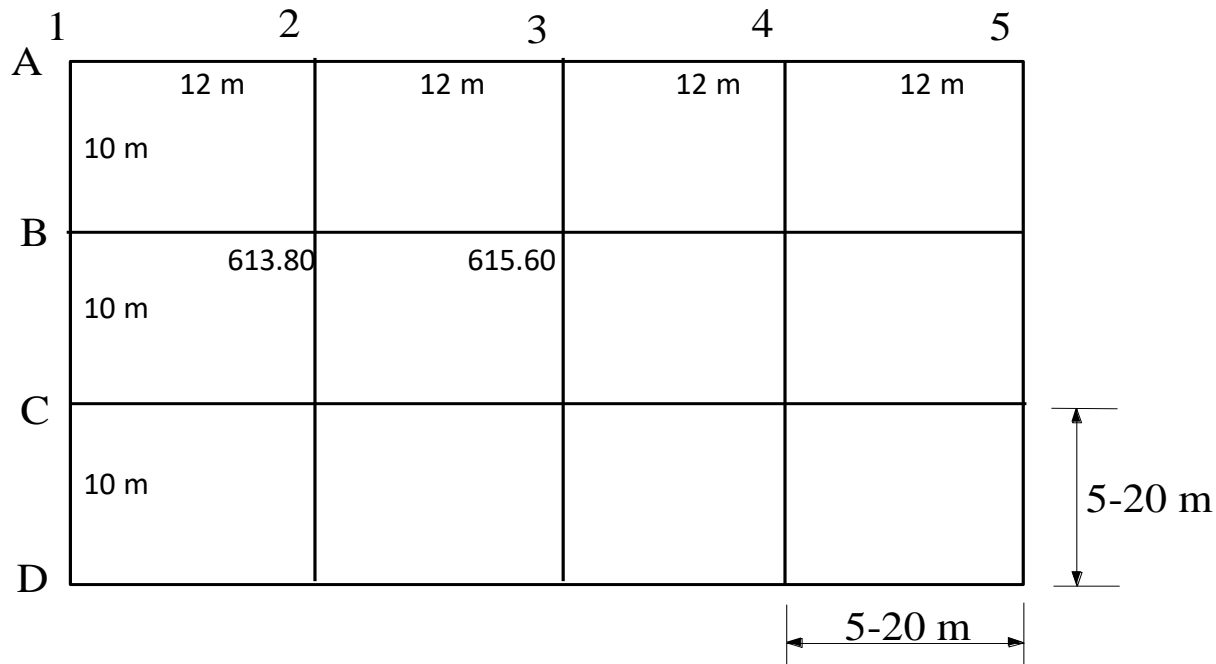
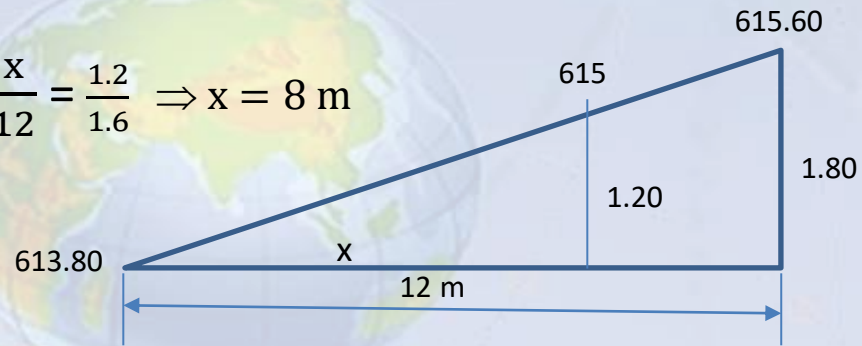


FIGURE 4.23: Gridding.

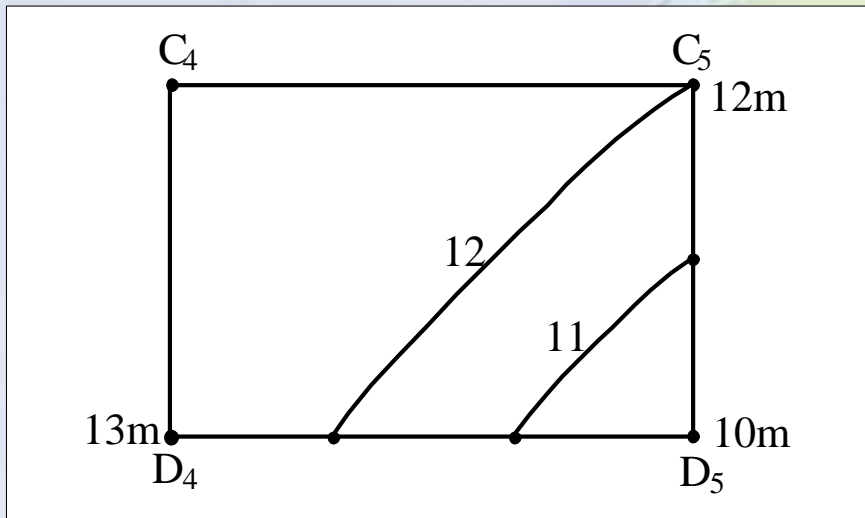


FIGURE 4.25: Plotting contour lines.

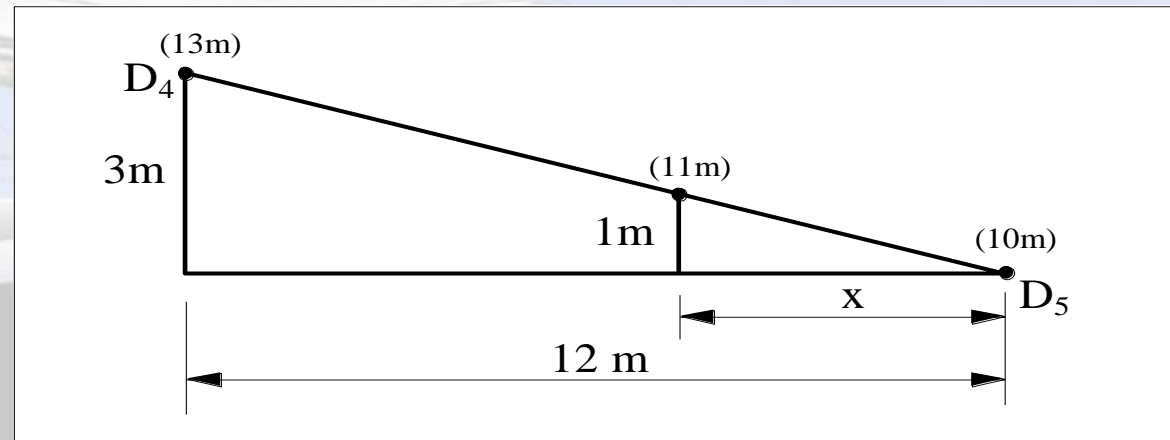


FIGURE 4.24: Linear interpolation.